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# Robotic-assisted abdominoperineal resection: technique, feasibility, and short-term outcomes

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## Abstract

**Aim:** The use of robotic-assisted laparoscopy seems fully adapted to pelvic surgery. However, few studies focus on robotic-assisted abdominoperineal resection (RAAPR). The aim of this study was to assess the feasibility, short-term postoperative outcomes, and pathological results of RAAPR. In addition, we provide a detailed description of the operative procedure and a brief review of the current literature.

**Methods:** Between January 2013 and April 2018, we performed a total of 428 robotic surgeries, including 294 colorectal resections (68.7%). Data were prospectively collected and included demographics, intraoperative findings, postoperative outcomes, and pathological data. For this study, we included the first 20 consecutive RAAPRs performed with the four-arm da Vinci Si surgical system (Intuitive Surgical Inc., Sunnyvale, CA, USA).

**Results:** Twenty patients (nine men) with a mean age of 68 years and a mean BMI of  $24.5 \pm 5.0$  kg/m<sup>2</sup> underwent RAAPR for low rectal adenocarcinoma (80%) or squamous cell carcinoma of the anal canal. Sixteen (80%) patients underwent preoperative pelvic radiotherapy and eight (40%) had a history of previous abdominal surgery. Mean operative duration was  $218 \pm 52$  min. There was no conversion to open surgery. Mortality, reoperation, and morbidity rate were 5%, 25%, and 60%, respectively. Three (15%) patients presented perineal complications. Mean length of hospital stay was 20 days. Three (15%) patients had pT4 tumor. Mesorectal excision was considered complete in 90%. On average,  $16.5 \pm 7.2$  lymph nodes were retrieved.



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**Conclusion:** RAAPR is feasible, with acceptable pathologic and short-term outcomes. The current literature does not demonstrate significant differences between robotic and laparoscopic APR. Indeed, we cannot justify its use in routine on the basis on the available evidence.

**Keywords:** Abdominoperineal resection, total mesorectal excision, robotic surgery, feasibility, rectal cancer, anal cancer

## INTRODUCTION

The frequency with which abdominoperineal resection (APR) is performed has dramatically decreased over the last decade, mostly due to technical advances, the need for shorter distal margins, and oncological therapeutic progress<sup>[1,2]</sup>. Despite this, APR remains the appropriate approach for rectal cancers with involvement of the sphincter complex or that cannot be removed with sufficient distal resection margins, and for elderly with poor baseline functional status<sup>[2]</sup>. Finally, APR remains the standard treatment for persistent or recurrent squamous cell carcinoma of the anal canal after chemoradiotherapy<sup>[3]</sup>.

Minimally invasive rectal surgery (MIRS) is a challenge<sup>[4]</sup>. The reported high conversion rates and the risks of positive circumferential resection margin (CRM) are thought to reflect the high level of difficulty associated with MIRS<sup>[5]</sup>. The fulcrum effect is one of the factors incriminated in the difficulty of MIRS, as it results in reduced motion ranges, especially inside the pelvis<sup>[6]</sup>. A robotic-assisted approach could potentially overcome some of the limitations of conventional laparoscopic rectal surgery<sup>[7]</sup>. However, few studies focus on robotic-assisted APR (RAAPR), and most are retrospective. Thus, the aim of this study was to provide a detailed description on the operative procedure, and to assess the feasibility, pathological, and short-term outcomes of the first 20 RAAPR in a high-volume center.

## METHODS

### Patients' selection and preoperative management

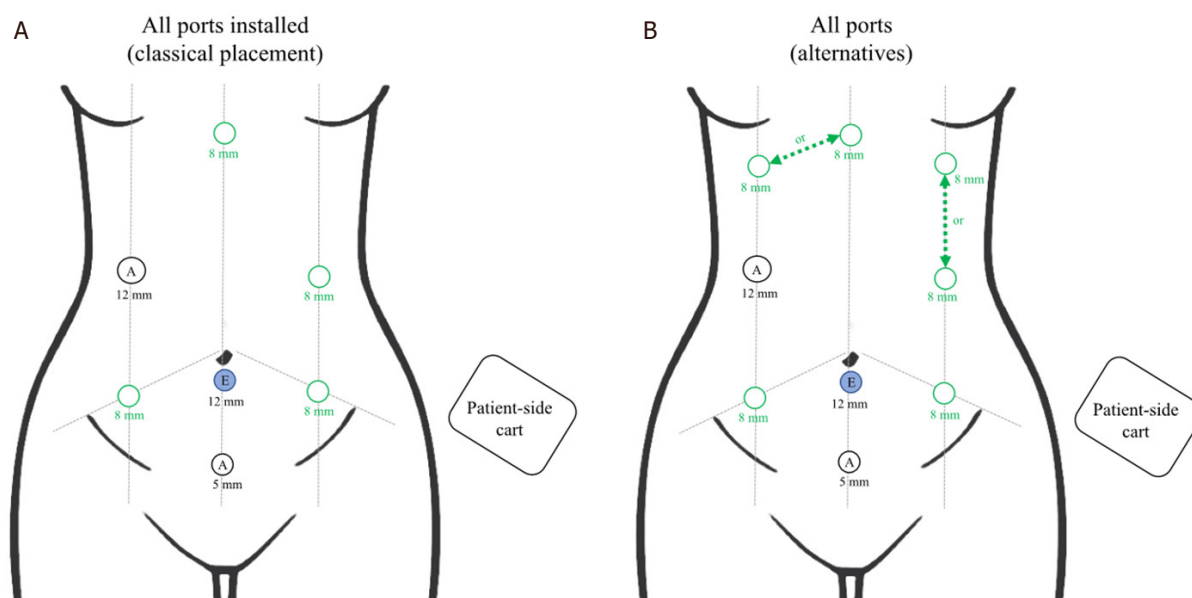
All consecutive patients undergoing RAAPR in our department from January 2013 to April 2018 were prospectively included. Patients with distant metastases were not excluded. Preoperative tumor staging assessment included colonoscopy; pelvic MRI; endorectal ultrasound when indicated; and thoracic, abdominal, and pelvic injected CT scan. Neoadjuvant treatment was planned according to the French guidelines<sup>[8]</sup> after multidisciplinary staff discussion.

### Postoperative care and follow-up

Histopathological mesorectal grade was classified according to Quirke *et al.*<sup>[9]</sup>. All patients were started on clear liquids at postoperative day 1, and then a soft diet on passage of gas in the stoma bag. Particular attention was made to the perineal wound healing. Patients were discharged once their pain was controlled on oral analgesics and when the healing of the perineal wound was considered satisfactory. No patient was included in any "Enhanced Recovery After Surgery" protocol. Surgical complications were evaluated during the 30-day postoperative period and were graded according to Dindo and Clavien<sup>[10]</sup>.

### Statistical analysis

Demographic data, operative parameters, and pathologic outcomes were recorded in a prospectively collected database. Quantitative variables were expressed as means ( $\pm$  standard deviation) and qualitative variables as frequencies (percentages). Statistical analyses were performed using SPSS (IBM SPSS Statistics, Version 23 for Macintosh; IBM Corp., Armonk, NY, USA).



**Figure 1.** Port placement for robot-assisted abdominoperineal resection: operative view with all ports installed (A); and alternative placements of the ports (B). A: assistant port; E: endoscope port

### Robotic-assisted abdominoperineal resection technique

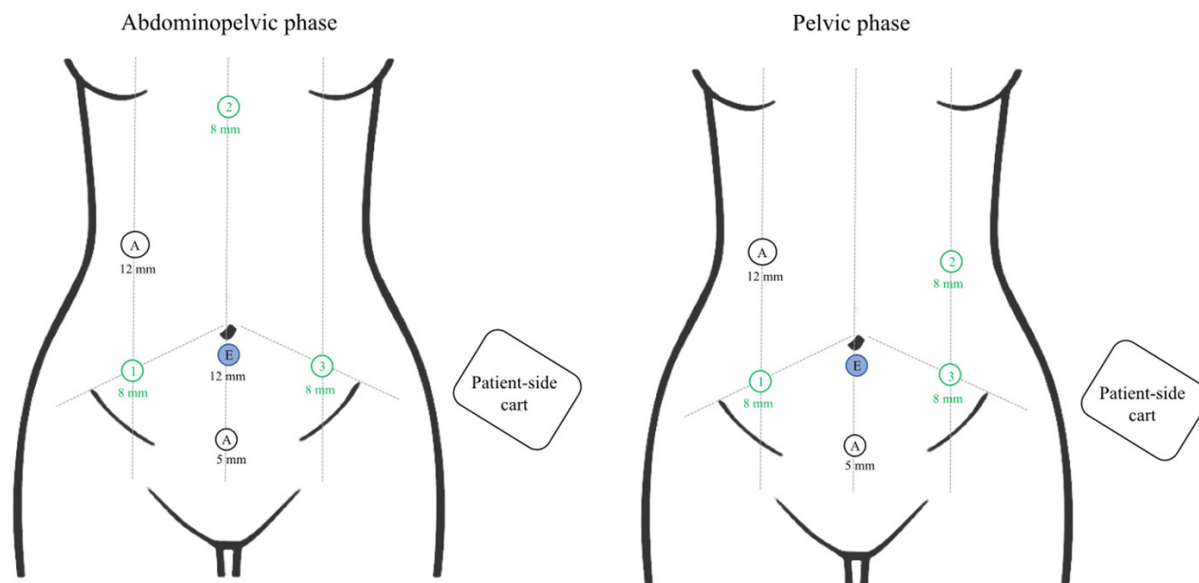
The technique described below used a totally robotic colorectal mobilization and consisted of an up-to-down approach (abdominopelvic, pelvic and perineal procedures), with cylindrical extralevator APR, using the four-arm da Vinci® Si surgical system (Intuitive Surgical Inc., Sunnyvale, CA, USA). The patient was placed in the lithotomy position, and the legs were placed in stirrups, in a 20° tilted Trendelenburg and right-roll position. Transurethral or suprapubic catheter was placed.

#### Port placement

Seven ports were usually used, including one 12-mm endoscope port, four 8-mm robotic operative ports, and one 12-mm and one 5-mm laparoscopic ports for the assistant, with the cart placed obliquely at the left antero-superior iliac spine [Figure 1A]. The 12-mm endoscope port was introduced through an infra-umbilical incision; a 30° endoscope was used for the abdominopelvic procedure, and then switched for a 0° endoscope for the pelvic dissection. One 8-mm robotic port was placed at the level of the xyphoid process (Arm 2, abdominopelvic phase), another one in the right iliac fossa (Arm 1, abdominopelvic and pelvic phases), another in the left iliac fossa (Arm 3, abdominopelvic and pelvic phases), and the last in the left flank (Arm 2, abdominopelvic phase) [Figure 2]. A 5-mm laparoscopic port for the assistant was placed above the pubis and a 12-mm laparoscopic assistant port was placed in the right flank [Figures 1 and 2]. The xyphoidian 8-mm port could be shifted in the right hypochondrium and the left flank 8-mm port could be placed in the left hypochondrium [Figure 1B].

#### Exploration and robot docking

The peritoneal cavity was explored to evaluate the presence of distant metastases (liver and peritoneal carcinomatosis). Adhesiolysis was performed laparoscopically if needed. The omentum was retracted to the supramesocolic compartment and the small bowel was retracted in the right side of inferior mesenteric vein axis in order to visualize the Treitz angle. The 30° camera was placed in the 12-mm port in the infra-umbilical region, and robotic Arms 1-3 were placed in the right lower quadrant port, in the subxyphoid port, and in the left iliac fossa port, respectively.



**Figure 2.** Port placement for robot-assisted abdominoperineal resection, in the abdominopelvic phase and in the pelvic phase. A: assistant port; E: endoscope port

### *Abdominopelvic procedure*

The APR started with a medial to lateral approach. The mobilization of the splenic flexure and the ligation of the inferior mesenteric vein at its origin were usually not necessary. The peritoneum was incised at the level of the sacral promontory. The avascular presacral plane was entered, and this plane was developed identifying the origin of the inferior mesenteric artery and the left ureter. During this phase, dissection was performed using monopolar curved scissors (Arm 1), with tissues held by a Cadiere forceps (Arm 3), while the mesocolon was retracted using a fenestrated bipolar forceps (Arm 2). The superior rectal artery was ligated at its origin from the inferior mesenteric artery using a laparoscopic clip applicator and cut. The mesenteric dissection was continued to the pelvic cavity along the prehypogastric fascia, preserving the pelvic autonomic nerves. The lateral approach was then performed with the incision of the Toldt's line, allowing complete sigmoid colon mobilization. The dissection was continued to the level of Gerota's fascia or the gastrocolic ligament, depending on the length of the sigmoid colon, and caudally to the level of the left peritoneal reflection. If the omentum was consistent, omentoplasty could be prepared by cutting right gastroepiploic vessels and mobilizing the omentum up to the left gastroepiploic pedicle.

### *Pelvic procedure*

The pelvic procedure continued with TME. At this point, the switch of ports was required to carry on the procedure: Arm 2 was retrieved from the subxiphoid port and placed on the left iliac fossa port [Figure 2]. The pelvic dissection proceeded posteriorly first with the opening of the avascular presacral plane, then laterally, and finally anteriorly. Arm 3 was used for retraction, and Arms 1 and 2 were used to develop a plane of dissection between the presacral plane and the mesorectum until the Waldeyer fascia at the level of the anorectal junction. The rectal proper fascia was identified and preserved, and dissection was performed using robotic monopolar scissors. Then, lateral mesorectal dissection was performed. Particular attention was made to preserve hypogastric nerves. After the incision of the peritoneal reflection, lateral pelvic attachments were divided distally, until the levator ani. Lastly, the anterior mesorectal dissection was performed. The lateral peritoneal incisions were connected anteriorly at the recto-uterine pouch in women and rectovesical recess in men. Using Cadiere forceps to retract the urinary bladder and seminal vesicles, dissection was made to separate the rectum from the seminal vesicles and prostate or vagina through the Denonvillier's fascia, followed by separation of the levator muscles. When pelvic floor was reached

**Table 1. Preoperative characteristics**

	Overall (n = 20)
Male (%)	9 (45)
Age in years (mean ± SD)	68.5 ± 14.1
Age ≥ 75 years (%)	7 (35)
BMI in kg/m <sup>2</sup> (mean ± SD)	24.5 ± 5.0
BMI > 30 kg/m <sup>2</sup> (%)	2 (10)
BMI < 18 kg/m <sup>2</sup> (%)	1 (5)
ASA score ≥ 2 (%)	17 (85)
History of prior abdominal surgery (%)	8 (40)
Indication of APR	
Low rectum adenocarcinoma (%)	18 (90)
Epidermoid carcinoma of the anal canal (%)	2 (10)
Pretreatment T4 tumor (%)	5 (25)
Neoadjuvant treatment	17 (85)
Chemotherapy (%)	1 (5)
Radiotherapy (%)	4 (20)
Radio-chemotherapy (%)	12 (60)

BMI: body mass index; APR: abdominoperineal resection

circumferentially around the rectum, the pelvic portion of the dissection was completed. The proximal portion of the colon was stapled and cut with an endostapler. A standard incision through the abdominal wall was then created at the intended colostomy site; the distal colon was brought through this incision; and the end colostomy was fashioned.

#### *Perineal procedure*

The perineal procedure was performed as previously described for open approach, in the lithotomy position (except for one patient, for whom it was performed in prone position because of hip dysplasia<sup>[11]</sup>): an elliptical incision was made around the anus outside the sphincter muscles. The ischioirectal fat was dissected until the levators plane was identified and cut. The section of the anococcygeal ligament gave access to the presacral space and the abdominal cavity. The specimen was extracted through the pelvic incision. Omentoplasty could be placed in the pelvic cavity at this point. The drains were positioned, and the perineal wound was closed.

## RESULTS

### **Patients' characteristics**

From January 2013 to April 2018, we performed a total of 428 robotic procedures, among which 294 colorectal resections (68.7%), including 20 consecutive RAAPR. We included nine men (45%). Mean age was 68.5 ± 14.1 years and mean BMI was 24.5 ± 5.0 kg/m<sup>2</sup>. Eight (40%) patients had prior abdominal surgery (appendectomy in four patients, cholecystectomy in three patients, and suture repair of a perforated duodenal peptic ulcer in one patient). The majority of patients underwent APR for low rectum adenocarcinoma and 17 (85%) patients received preoperative treatment. Demographic data are summarized in [Table 1](#).

### **Operative characteristics**

All patients underwent robotic-assisted rectal resection with TME and cylindrical extralevator APR with total excision of the levator muscle. The mean total operating duration was 218.1 ± 52.5 min. Mean operative console time was 96.2 ± 48.0 min and perineal approach duration was 50 ± 30.0 min. Four robotic arms were used in 80% of the cases. Six ports were used in 70% of the patients. Fifteen (75%) procedures required robotic arm realignment. Six (30%) patients with fatty mesocolon required left colonic mobilization with section of the inferior mesenteric vein at its ending at the bottom edge of the pancreas,

**Table 2. Intraoperative characteristics**

	Overall (n = 20)
Total operative duration in minutes (mean ± SD)	218.1 ± 52.5
Operative console time in minutes (mean ± SD)	96.2 ± 38.3
Proctectomy duration in minutes (mean ± SD)	96.2 ± 48.0
Perineal approach duration in minutes (mean ± SD)	50 ± 30
Number of robotic arms	
3 arms (%)	4 (20)
4 arms (%)	16 (80)
Number of ports	
4 ports (%)	3 (15)
5 ports (%)	2 (10)
6 ports (%)	14 (70)
7 ports (%)	1 (5)
Necessity of robotic arm realignment (%)	15 (75)
Number of robotic arm realignment	
1 robotic arm realignment (%)	3 (15)
2 robotic arm realignments (%)	12 (60)
Splenic flexure mobilization (%)	3 (15)
Section of the inferior mesenteric vein (%)	6 (30)
Section of the inferior mesenteric artery (%)	11 (55)
Total mesorectal excision (%)	20 (100)
Specimen retrieval site	
Perineal incision (%)	19 (95)
Supra-pubic incision (%)	1 (5)
Omental pedicle flap placement (%)	5 (25)
Associated procedures (%)	6 (30)
Pelvic drainage (%)	20 (100)
Conversion to open (%)	0
Intraoperative complications (%)	2 (10)
Bleeding (%)	1 (5)
Tumor efferaction (%)	1 (5)
Intraoperative bleeding in mL (mean ± SD)	297.5 ± 420.0

and splenic flexure mobilization for three (15%) of them. Specimen retrieval was conducted through the perineal incision in 95% of the patients and all had terminal colostomy. Associated omentoplasty was performed in five (25%) patients. The following associated procedures were performed in six (30%) patients: incisional hernia repair ( $n = 1$ ), resection of an ovarian cyst ( $n = 1$ ), partial resection of the posterior wall of the vagina ( $n = 1$ ), partial prostatectomy ( $n = 1$ ), partial resection of the posterior wall of the prostatic urethra and urethroplasty ( $n = 1$ ), and partial sacrectomy ( $n = 1$ ). No conversion to open surgery was required in this series. Macroscopic intraoperative tumor efferaction occurred in one patient (5%). Mean intraoperative blood loss was 297 mL. Intraoperative variables and outcomes are summarized in [Table 2](#).

### Postoperative outcomes

One patient (5%) died at Postoperative Day 14 because of respiratory failure in the context of septic shock secondary to a *Clostridium difficile* colitis. Morbidity rate was 60%, with seven (35%) medical complications and nine (45%) surgical complications. Six patients (30%) presented a severe complication (Dindo-Clavien  $\geq 3$ ), which required reoperation in five (25%). Perineal wound complication occurred in three (15%) patients who presented complete disunion of the perineal wound and required iterative vacuum therapy until complete healing. These three patients had undergone preoperative 45 Gy pelvic irradiation and two of them had omental pedicle flap placement. The duration of hospital stay for these three patients was 29, 65, and 66 days, respectively. Four (20%) patients presented pelvic abscesses, which were treated conservatively by antibiotherapy. Two patients (10%) had ureteral fistula (one patient required reoperation and ureteral reimplantation, and the other was conservatively treated by ureteral catheter placement). The mean hospital length of stay was 20.4 days. Postoperative outcomes are summarized in [Table 3](#).



**Table 3. Postoperative outcomes**

	Overall (n = 20)
Mortality (%)	1 (5)
Morbidity (%)	8 (40)
Medical complications (%)*	7 (35)
Urinary tract infection (%)	5 (25)
Acute urinary retention (%)	2 (10)
Malnutrition (%)	2 (10)
Pulmonary infection (%)	1 (5)
Septic shock (%)	1 (5)
Clostridium colitis (%)	1 (5)
Ileus (%)	1 (5)
Surgical complications (%)*	9 (45)
Pelvic abscess (%)	4 (20)
Perineal wound disunion (%)	3 (15)
Ureteral fistula (%)	1 (5)
Incisional abscess (%)	2 (10)
Clavien-Dindo > 2 (%)	6 (30)
Complications requiring reoperation (%)	5 (25)
Hospital length of stay in days (mean ± SD)	20.4 ± 17.1
Hospital length of stay > 7 days (%)	17 (85)

\*Several patients presented more than one complication

### Pathologic outcomes

Pathological results are presented in [Table 4](#). A complete pathologic response was observed in one patient (5%). Three patients (15%) presented a pT4 tumor on final pathological report. On average, 16.5 lymph nodes were retrieved. The mean tumor size was 4.6 cm. Mesorectum was complete in 18 patients (90%).

### DISCUSSION

Our study showed that RAAPR is feasible, with satisfying pathological results and acceptable postoperative outcomes.

During the last decade, the use of the robotic system has progressed<sup>[12]</sup>. Proctectomy can be technically hazardous with the straight instruments and limited retraction provided by laparoscopy. Robotic-assisted pelvic dissection can be potentially associated with better autonomic nerve preservation, lower conversion rate, and less blood loss<sup>[13]</sup>. Despite its theoretical advantages, the benefits of the mini-invasive approach compared to open surgery in rectal surgery are still under debate, and it is even more questionable for the robotic approach<sup>[14]</sup>. Indeed, the only existing randomized clinical trial (ROLARR) comparing the robotic-assisted vs. conventional laparoscopic surgery for rectal cancer showed that the robotic approach did not significantly reduce the conversion rate<sup>[15]</sup>. There were also no differences between the two groups in terms of intraoperative complications, postoperative mortality and morbidity, and positive CRM. The interest of robotic assistance in APR is even more challenging to demonstrate since very few studies in the literature focus on RAAPR [[Table 5](#)]. We found only four studies that included more than 20 patients: three studies compared RAAPR to open APR<sup>[16,17]</sup> or to open APR and laparoscopic APR<sup>[18]</sup>, and one non-comparative study<sup>[19]</sup> focused on RAAPR. The ROLARR trial, for its part, did not analyze the outcomes in its specific sub-population of 52 RAAPR.

Compared to the conventional laparoscopic approach, the benefits of the robotic upgraded handling on the patient outcomes are difficult to bring to light. Indeed, up to now, robotic assistance seems to remain equivalent to laparoscopy. In the current study, the operative duration was 218.1 ± 52.5, which is in line with the data in the literature [[Table 5](#)] and longer than laparoscopic APR<sup>[18]</sup>. No conversion was required

**Table 4. Pathologic outcomes**

	Overall (n = 20)
Tumor regression grade (n = 15)	
No response (%)	3 (25)
Minimal (%)	7 (35)
Moderate (%)	3 (25)
Near total (%)	1 (5)
Complete (%)	1 (5)
Tumor histology	
Adenocarcinoma (%)	18 (80)
Epidermoid carcinoma (%)	2 (10)
pAJCC stage	
Stade 0 (%)	1 (5)
Stade I (%)	1 (5)
Stade II (%)	6 (30)
Stade III (%)	10 (50)
Stade IV (%)	2 (10)
pT-category	
pT0 (%)	2 (10)
pT1 (%)	0
pT2 (%)	2 (10)
pT3 (%)	13 (65)
pT4 (%)	3 (15)
pN-category	
pN0 (%)	10 (50)
pN1 (%)	4 (20)
pN2 (%)	6 (30)
pM-category	
pM0 (%)	18 (90)
pM1 (%)	2 (10)
Number of retrieved lymph nodes (mean ± SD)	16.5 ± 7.2
Number of metastatic lymph nodes (mean ± SD)	1.9 ± 2.9
CRM positive, ≤ 1 mm (%)	4 (20)
CRM depth in mm (mean ± SD)	2.3 ± 1.9
Tumor perforation (%)	2 (10)
Mesorectal grade	
Incomplete (%)	1 (5)
Nearly complete (%)	1 (5)
Complete (%)	18 (90)
Distal margin in cm (mean ± SD)	3.2 ± 1.9
Tumor size in cm (mean ± SD)	4.6 × 3.9 ± 0.3

in our study and Moghadamyeghaneh *et al.*<sup>[18]</sup> showed a significantly decreased conversion rate for RAAPR compared to laparoscopic APR (5.7 vs. 13.4%).

The robotic approach presents technical drawbacks, mostly associated with the loss of haptic feedback. Actually, despite the massive help of the immersive 3D overview, vibration, pressure, or shearing forces are not always apparent<sup>[13]</sup>. A recent analysis of 509,029 patients who underwent elective colectomy in the United States from 2009 to 2012 showed that the rate of iatrogenic complications was increased for robotic surgery<sup>[20]</sup>.

Noteworthy, the results presented here are worse than our previously published results for sphincter-saving procedures<sup>[21]</sup>. The morbidity rate was 60%, with mainly perineal wound disunions and urinary complications. The mean length of hospital stay was three weeks, which is longer than in other studies in the literature [Table 5]. In this series, no patient was included in any “Enhanced Recovery After Surgery” program, and perineal wound complications were associated with longer hospital stay. Indeed, three



**Table 5. Summary of the relevant literature about robotic-assisted abdominoperineal resection**

First author, study period, type of study	Number of RAAPR	BMI > 30 kg/m <sup>2</sup> n (%)	History of prior abdominal surgery n (%)	Preoperative treatment n (%)	Conversion to open n (%)	Mean operative time (min)	TME operative time (min)	Intraoperative bleeding (mL)	Intraoperative tumor perforation n (%)	30-day mortality n (%)	30-day morbidity n (%)	LOS (days)	pT4 tumors n (%)	Positive CRM n (%)
Present study 2013-2018	20	2 (10)	8 (40)	17 (85)	0	218.1 ± 52.5	96.2 ± 48	297.5 ± 420.0	1 (5)	1 (5)	8 (40)	20.1 ± 17.1	3 (15)	4 (20)
Retrospective Kim et al. <sup>[17]</sup> 2011-2013	21	-	4 (19)	19 (91)	0	197 ± 29	-	-	0	0	4 (19)	7.6 ± 1.6	1 (4.8)	0
Prospective RAAPR vs. OAPR Kim et al. <sup>[16]</sup> 2010-2016	40	-	6 (15)	37 (93)	0	215 ± 56	-	> 400 mL: 5 (13)	2 (5)	0	-	8 ± 2.8	1 (3)	1 (3)
Retrospective RAAPR vs. OAPR Moghadamyeghaneh et al. <sup>[8]</sup> 2009-2012	872	59 (6.8)	-	-	50 (5.7)	-	-	-	-	Too small to report	235 (26.9)	8 ± 6	-	-
Retrospective OAPR vs. LAPR vs. RAAPR Eftaiha et al. <sup>[19]</sup> 2007-2012	22	8 (36.4)	10 (45.5)	20 (90.9)	1 (4.5)	380 ± 91	114 ± 37	259 ± 75	1 (4.5)	1 (4.5)	16 (72.7)	6 (36)	-	3 (13.6)

APR: Abdominoperineal resection; BMI: body mass index; LAPR: laparoscopic abdominoperineal resection; LOS: length of hospital stay; OAPR: open abdominoperineal resection; RAAPR: robotic-assisted abdominoperineal resection

patients had complete perineal wound disunion, which required iterative vacuum therapy under general anesthesia. Two of these three patients presenting perineal wound complication had an omentoplasty, which created an interface between the bowel and the aspirative foam and helped to avoid bowel injuries. In addition, recent series showed that the usefulness of omentoplasty was limited when compared to primary perineal closure<sup>[22-24]</sup>. Noteworthy, in a recent publication, omentoplasty was not associated with a lower rate of perineal wound dehiscence<sup>[25]</sup> or a lower rate of non-healing perineal wound<sup>[22]</sup>, while it was associated with organ space infection<sup>[24]</sup> after APR.

Oncological benefits could be expected from improved dissection techniques in the pelvis, and better-quality APR allowed by the theoretical advantages of the robotic approach. Indeed, open and laparoscopic APR are still associated with high local recurrence, because of higher positive CRM and tumor perforation<sup>[25]</sup>. In the literature, RAAPR did not show superiority to the open approach or the laparoscopic approach in terms of histopathological quality of the rectal resection<sup>[15-17,26]</sup> and initial oncological outcome<sup>[15,16,26]</sup>.

In our study, all procedures were performed by senior surgeons trained in robotic surgery and complete resection of the mesorectum was obtained in 90%. These senior surgeons also had more than 15 years of experience in laparoscopic and open surgery for rectal cancer. CRM was positive in four patients (20%),

among whom two patients had a pT4 tumor. In our study, postoperative positive CRM was not suspected in the preoperative oncologic assessment for these patients. However, this high rate of positive CRM raises the issue of preoperative patients' selection. Upfront open APR could be chosen over RAAPR according to parameters that take into account the specificities of the robotic approach.

Any proposal for the routine utilization of robotic assistance in surgery requires a proof of clinical benefit, while considering the associated full set of costs. Indeed, even if MIRS has been shown to be associated with lower morbidity rate, reduced pain, and early return to work, there are not enough data to state that oncological results are equivalent<sup>[14]</sup>. Added to the difficulty in proving its clinical benefits, the use of robotic approach in APR outside clinical studies remains questionable.

## DECLARATIONS

### Authors' contributions

Data acquisition, data analysis, manuscript drafting, manuscript revision: Abdalla S

Data acquisition, manuscript revision: Valverde A, Fléjou JF, Goasguen N, Oberlin O

Study design, data analysis, manuscript drafting, manuscript revision, final approval: Lupinacci RM

### Availability of data and materials

Not applicable.

### Financial support and sponsorship

None.

### Conflicts of interest

All authors declared that there are no conflicts of interest.

### Ethical approval and consent to participate

This study was conducted according to the ethical standards of the local institutional committee on human experimentation and the consent form of all patients was obtained.

### Consent for publication

Not applicable.

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